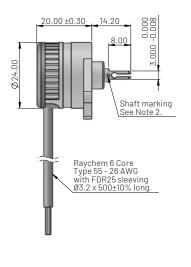
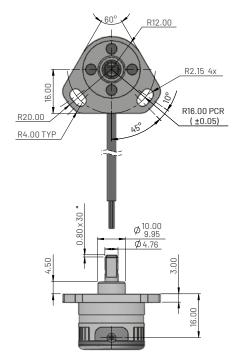
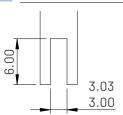


Dimensions for MHR5610 - Triangular flange mounting with a sprung shaft





Driving side detail



Ordering code

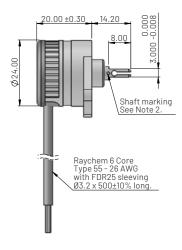
MHR5610 XV-XXX

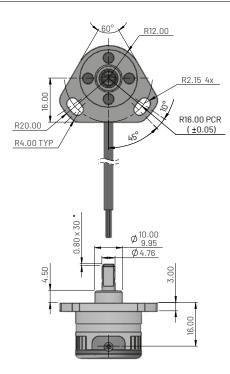
Output direction (viewed on shaft)

- C = Clockwise
- A = Anticlockwise
- D = Channel 1 output anticlockwise Channel 2 output clockwise

Electrical angle in degrees

Dimensions for MHR5620 - Triangular flange mounting with a round shaft





Ordering code

MHR5620 XV-XXX

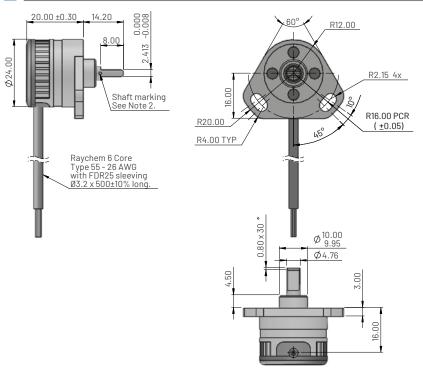
Output direction (viewed on shaft)

- C = Clockwise
- A = Anticlockwise
- D = Channel 1 output anticlockwise Channel 2 output clockwise

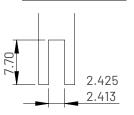
Electrical angle in degrees



Dimensions for MHR5630 - Triangular flange mounting with a blade shaft



Driving side detail



Ordering code

MHR5630 XV-XXX

Output direction (viewed on shaft)

- C = Clockwise
- A = Anticlockwise
- D = Channel 1 output anticlockwise Channel 2 output clockwise

Electrical angle in degrees

Electrical and mechanical specification for MHR5600 Series

Input specification			
Supply voltage (Vs)	5.0±10% regulated	8 to 30 unregulated	VDC
Over voltage protection	Up to 50		VDC
Supply current	<15		mA
Reverse polarity protection	Up to -10		VDC
Power on settlement time	<100		ms
Input voltage rise time	0.25 minimum		V/ms
Output specification			·
Output type	Analogue voltage		
Output direction	Clockwise or anticlockwise (specified at time of order)		
Voltage output (lout)	0-Vs(+5)	0 - 5.0	mA
Line regulation	Ratiometric with Vs	<0.01	%FS
Monotonic range	Linear Range (see note 6)		
Load resistance (max)	>10K		Ohms
Output noise	<5		mV RMS
Performance specification			·
Measurement range	20 to 360 in 1° increments		0
Resolution	0.025		% of measurement range
Non-linearity (Note 4)	<±0.25		%FS
Temperature coefficient (Vout)	<±0.003	<±0.011	%FS/°C
Update rate (nominal)	500		Hz
Max operating speed	600		RPM
General specification			
Weight (approx.)	30		grams
Protection/sealing	Electronic housing IP68 and IP69K		
Life	>500 million cycles		dependant on environment
Dither life	Contactless - no degradation due to shaft dither		
Operational temperature	-40 to +150	See de-rating graph	°C
Storage temperature	-55 to +150		°C
Materials	Case: Aluminium 6082, Top cap: GF polymer, Shaft: Stainless steel 316		

MHR5600 Series

Magnetic Hall rotary position sensor



Notes

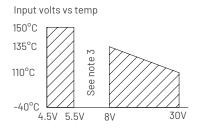
- 1. Incorrect wiring may cause internal damage.
- 2. When shaft marking is facing cable exit, instrument is mid-travel (2.5V output).
- 3. Do not operate between 5.5V and 8V.
- 4. Non-linearity is calculated from least squares best fit method over the Linear Range.
- 5. Phasing for the MHR5610 DV-XXX option is at mid-travel only.
- 6. Linear Range = Measurement range x 0.995 Nom.
- 7. Due to hall effect technology used in this device, ferrous materials and magnetic fields close to the sensor may influence output.
- 8. General dimension tolerance is ± 0.25 .

Electrical connections (see note 1)

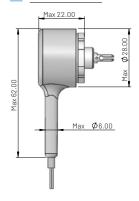
	Wire Colour	Function	
Channel 1	Red	Supply Voltage (Vs)	
	White	Output Voltage (Vout)	
	Black	Ground	
Channel 2	Blue	Supply Voltage (Vs)	
	Yellow	Output Voltage (Vout)	
	Green	Ground	

Typical output +5V (see note 6) Linear Range Measurement Range

Input voltage de-rating graph



Accessories



Boot dimensions when fitted (Boot supplied seperately)

Boot

Part No: JN025-002

1 411110: 011020 002	
	Material
	Polyolefin

Contact (Europe)

Active Sensors Ltd, Unit 12, Wilverley Road, Christchurdch, Dorset, BH23 3RU, UK

Contact (North America)

Active Sensors Inc, 8520 Allison Pointe Blvd, Suite 220, Indianapolis, IN 46250, USA